

## Stochastic Integrals.

In defining the integral

$$I = \int_0^T f(s) dx(s)$$

the Lebesgue theory assumes that  $f(\cdot)$  is a bounded continuous function and  $x(s)$  is a function of bounded variation so that  $dx$  can be thought of as a measure on  $[0, T]$ . With that we get the bound

$$(1) \quad |I| \leq \sup_{0 \leq s \leq T} |f(s)| \text{Var}_{[0, T]} x(\cdot)$$

where

$$\text{Var}_{[0, T]} x(\cdot) = \sup_{\mathcal{P}} \sum_{i=0}^{n-1} |x(t_{i+1}) - x(t_i)|$$

where  $\mathcal{P} = \{0 = t_0 < t_1 < t_2 \cdots < t_n = T\}$  is an arbitrary partition of  $[0, T]$ . It is calculated as the limit of the sum

$$I_n = \sum f(x(\tau_i)) [x(t_{i+1}) - x(t_i)]$$

where  $t_i \leq \tau_i \leq t_{i+1}$  are arbitrary points. The estimate (1) comes from the worst possible case where there are no cancellations and

$$\begin{aligned} |I| &= \lim |I_n| \leq \sum_{i=0}^{n-1} |f(x(\tau_i))| |x(t_{i+1}) - x(t_i)| \\ &\leq \sup_{0 \leq s \leq T} |f(s)| \lim_{n \rightarrow \infty} \sum_{i=0}^{n-1} |x(t_{i+1}) - x(t_i)| \\ &= \sup_{0 \leq s \leq T} |f(s)| \text{Var}_{[0, T]} x(\cdot) \end{aligned}$$

However if  $x(\cdot)$  is random we can do better. Let  $x(\cdot)$  be Brownian motion. we will define the "Wiener Stochastic Integral"

$$I(f) = \int_0^T f(s) dx(s)$$

Let us assume that  $f$  is a simple function  $f = f_i$  on  $[t_i \leq t \leq t_{i+1}]$ . Then

$$I(f) = \sum_i f_i [x(t_{i+1}) - x(t_i)]$$

is a Gaussian random variable with mean 0 and variance

$$E[I(f)^2] = \sum_i |f_i|^2 (t_{i+1} - t_i) = \int_0^T |f(t)|^2 dt$$

If  $f$  is a square integrable function on  $[0, T]$  it can be approximated by a sequence  $f_n$  of simple functions in  $L_2[0, T]$ . Then

$$\lim_{n, m \rightarrow \infty} E[|I(f_n) - I(f_m)|^2] = \lim_{n, m \rightarrow \infty} \int_0^T |f_n(t) - f_m(t)|^2 dt = 0$$

Hence

$$I(f) = \lim_{n \rightarrow \infty} I(f_n)$$

exists on  $L_2(P)$  where the Brownian motion is defined so long as  $\int |f(t)|^2 dt < \infty$ .  $I(f)$  has a Gaussian distribution with mean 0 and variance  $\int_0^T |f(t)|^2 dt$ . Note that each  $I(f)$  is defined only almost surely as a member in  $L_2(P)$ .

We need to do this because almost surely Brownian motion is NOT of bounded variation. Since Brownian paths are almost surely continuous, if they were of bounded variation, then

$$\lim_{n \rightarrow \infty} \sum [x(t_{i+1}) - x(t_i)]^2 \leq \sup_i |x(t_{i+1}) - x(t_i)| \text{Var}_{[0, T]}(x(\cdot)) = 0$$

On the other hand

$$\begin{aligned} E\left[\left(\sum [x(t_{i+1}) - x(t_i)]^2 - T\right)^2\right] &= E\left[\sum \left([x(t_{i+1}) - x(t_i)]^2 - (t_{i+1} - t_i)\right)^2\right] \\ &= \sum E\left[\left([x(t_{i+1}) - x(t_i)]^2 - (t_{i+1} - t_i)\right)^2\right] \\ &= \sum 2(t_{i+1} - t_i)^2 \end{aligned}$$

and therefore  $\sum [x(t_{i+1}) - x(t_i)]^2$  goes to  $T$  in  $L_2$  and not to 0.

In Wiener's stochastic integral  $f(t)$  is a non-random function. But in Itô's theory,  $f(t, \omega)$  can depend on the past history up to time  $t$  and not on the future. Consider a partition  $0 = t_0 < t_1 < \dots < t_n = T$ . Functions  $f_i(\omega)$  that are bounded measurable with respect to  $\mathcal{F}_{t_i}$ . Note that  $x(t)$  is a Brownian motion with respect to  $\mathcal{F}_t$ . Then if

$$f(t, \omega) = \sum_i f_i(\omega) \mathbf{1}_{[t_i, t_{i+1})}(t)$$

i.e. it equals  $f_i$  on  $[t_i, t_{i+1}]$  then the natural definition of the integral is

$$S(f, [0, T]) = \int_0^T f(s, \omega) dx(s) = \sum_{i=0}^{n-1} f_i(\omega) [x(t_{i+1}) - x(t_i)]$$

We denote the class of such  $f$ 's by  $\mathbf{F}$ . The increment  $(x(t_{i+1}) - x(t_i))$  is independent of  $\mathcal{F}_{t_i}$  and an easy computation yields

$$E[S(f, [0, T])] = 0 \quad \text{and} \quad E[S(f, [0, T])^2] = E\left[\int_0^T f(s, \omega)^2 ds\right]$$

and if we define for  $t_k \leq t \leq t_{k+1}$

$$\xi(t) = S(f, [0, t]) = \int_0^t f(s, \omega) dx(s) = \sum_{i=0}^{k-1} f_i(\omega)[x(t_{i+1}) - x(t_i)] + f_k(\omega)[x(t) - x(t_k)]$$

then  $(\xi(t), \mathcal{F}_t)$  is a martingale. It is square integrable and

$$\xi(t)^2 - \int_0^t f(s, \omega)^2 ds$$

is again a  $\mathcal{F}_t$  martingale. From Doob's inequality

$$E[\sup_{0 \leq t \leq T} |\xi(t)|^2] \leq 4E[\int_0^T |f(s, \omega)|^2 ds]$$

In order to define the Itô stochastic integral for  $f$  we need to know if we can approximate  $f$  by  $f_n \in \mathbf{F}$  in the sense that

$$E[\int_0^T |f_n(s, \omega) - f(s, \omega)|^2 ds] \rightarrow 0$$

A function  $f : [0, T] \times \Omega \rightarrow R$  is progressively measurable if for every  $t \in [0, T]$  the function  $f(s, \omega) : [0, t] \times \Omega \rightarrow R$  is (jointly) measurable as a map of  $[[0, t] \times \Omega, \mathcal{B}[0, t] \times \mathcal{F}_t] \rightarrow [R, \mathcal{B}(R)]$ . If  $f$  is progressively measurable then

$$\int_0^t |f(s, \omega)|^2 ds$$

is again progressively measurable and it makes sense to talk about square integrable progressively measurable functions, i.e. those for which

$$E\left[\int_0^T |f(s, \omega)|^2 ds\right] < \infty$$

Let us call this class  $\mathbf{F}_2$ . We define stochastic integrals for such functions by the following steps.

**Step 1.** We need to show that any  $f \in \mathbf{F}_2$  can be approximated by  $f_n \in \mathbf{F}$  such that

$$\lim_{n \rightarrow \infty} \|f_n - f\|_{[0, T]}^2 = E\left[\int_0^T |f_n(s, \omega) - f(s, \omega)|^2 ds\right] = 0$$

It would then follow that  $\xi_n(t, \omega) = \int_0^t f_n(s, \omega) ds$  satisfies

$$\lim_{n, m \rightarrow \infty} E[\sup_{0 \leq t \leq T} |\xi_n(t) - \xi_m(t)|^2] = 0$$

There is then the limit  $\xi$  of  $\xi_n$  that is progressively measurable and almost surely continuous. Moreover  $\xi(t)$  would be a martingale as would  $[\xi(t)]^2 - \int_0^t [f(s, \omega)]^2 ds$ .

**Step 2.** If  $f(t, \omega)$  is uniformly bounded and continuous in  $t$  for almost all  $\omega$ , then  $f_n(t, \omega) = f(\frac{[nt]}{n}, \omega)$  will work.

**Step 3.** If  $f(t, \omega)$  is bounded and progressively measurable then

$$f_n(t, \omega) = \frac{1}{h} \int_{(t-h) \vee 0}^t f(s, \omega) ds$$

is an almost surely continuous, bounded, progressively measurable approximation of  $f$ .

**Step 4.** Finally if  $f \in \mathbf{F}_2$ , we can truncate and choose  $f_n = f$  if  $|f| \leq n$  and  $f_n = 0$  otherwise. Then  $f_n$  is clearly progressively measurable, bounded and approximates  $f$ . This way for each  $f \in \mathbf{F}_2$  we define

$$\xi(t, \omega) = \int_0^t f(s, \omega) dx(s)$$

that satisfies the properties: it is almost surely continuous, and with respect to  $\mathcal{F}_t$ , both  $\xi(t, \omega)$  and  $[\xi(t, \omega)]^2 - \int_0^t [f(s, \omega)]^2 ds$  are martingales.

If  $f$  is bounded then

$$\exp[\lambda x(t) - \frac{\lambda^2}{2} \int_0^t [f(s, \omega)]^2 ds]$$

is a martingale with respect to  $\mathcal{F}_t$ . In general (if  $f$  is unbounded) it may only be a super-martingale (Fatou's lemma).

Example: Let us calculate  $\int_0^t x(s) dx(s)$ . One can pretend that  $x(s)$  is bounded. Then

$$\begin{aligned} \int_0^t x(s) dx(s) &= \lim_{\mathcal{P}} \sum x(t_j)(x(t_{j+1}) - x(t_j)) \\ &= \lim_{\mathcal{P}} \frac{1}{2} \sum [(x(t_{j+1}) + x(t_j))(x(t_{j+1}) - x(t_j))] \\ &\quad - \lim_{\mathcal{P}} \frac{1}{2} \sum [(x(t_{j+1}) - x(t_j))(x(t_{j+1}) - x(t_j))] \\ &= \lim_{\mathcal{P}} \frac{1}{2} \sum [(x(t_{j+1})^2 - x(t_j)^2)] - \lim_{\mathcal{P}} \frac{1}{2} \sum (x(t_{j+1}) - x(t_j))^2 \\ &= \frac{1}{2} [x(t)^2 - t] \end{aligned}$$

In other words  $dx(t)^2 = 2x(t)dx(t) + dt$ . More generally Itô's formula says

$$df(x(t)) = f'(x(t))dx(t) + \frac{1}{2} f''(x(t))dt$$

Sketch of proof.

$$\begin{aligned} f(x(t)) - f(x(s)) &= \sum_j f(x(t_{j+1})) - f(x(t_j)) \\ &\simeq \sum f'(x(t_j))[x(t_{j+1}) - x(t_j)] + \frac{1}{2} \sum f''(x(t_j))[x(t_{j+1}) - x(t_j)]^2 \\ &\quad + \sum O(|x(t_{j+1}) - x(t_j)|^2) \end{aligned}$$

The first term goes to  $\int_0^t f'(x(s))dx(s)$ . The third term goes to 0, because  $E[|x(t) - x(s)|^3] \simeq t^{\frac{3}{2}}$ . The second term goes to

$$\frac{1}{2} \int_0^t f''(x(s))ds$$